

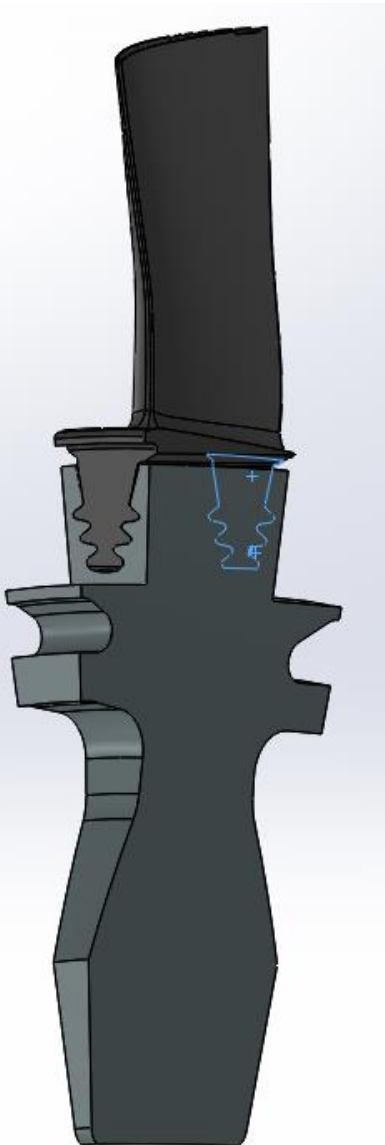
# DEVELOPMENT OF ADVANCED CRITERIA FOR BLADE ROOT DESIGN AND OPTIMIZATION

Farhad Alinejad

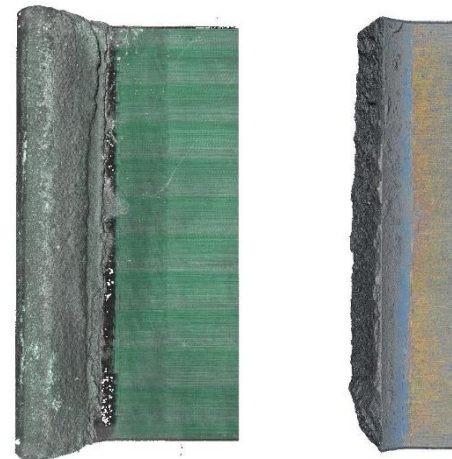
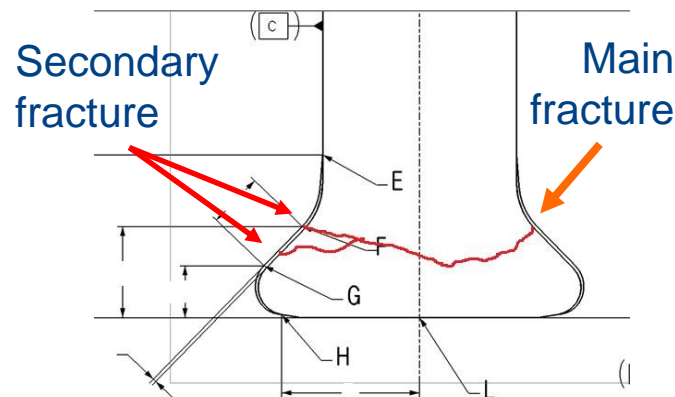
No. S221058

Under supervision of  
Prof. Daniele Botto

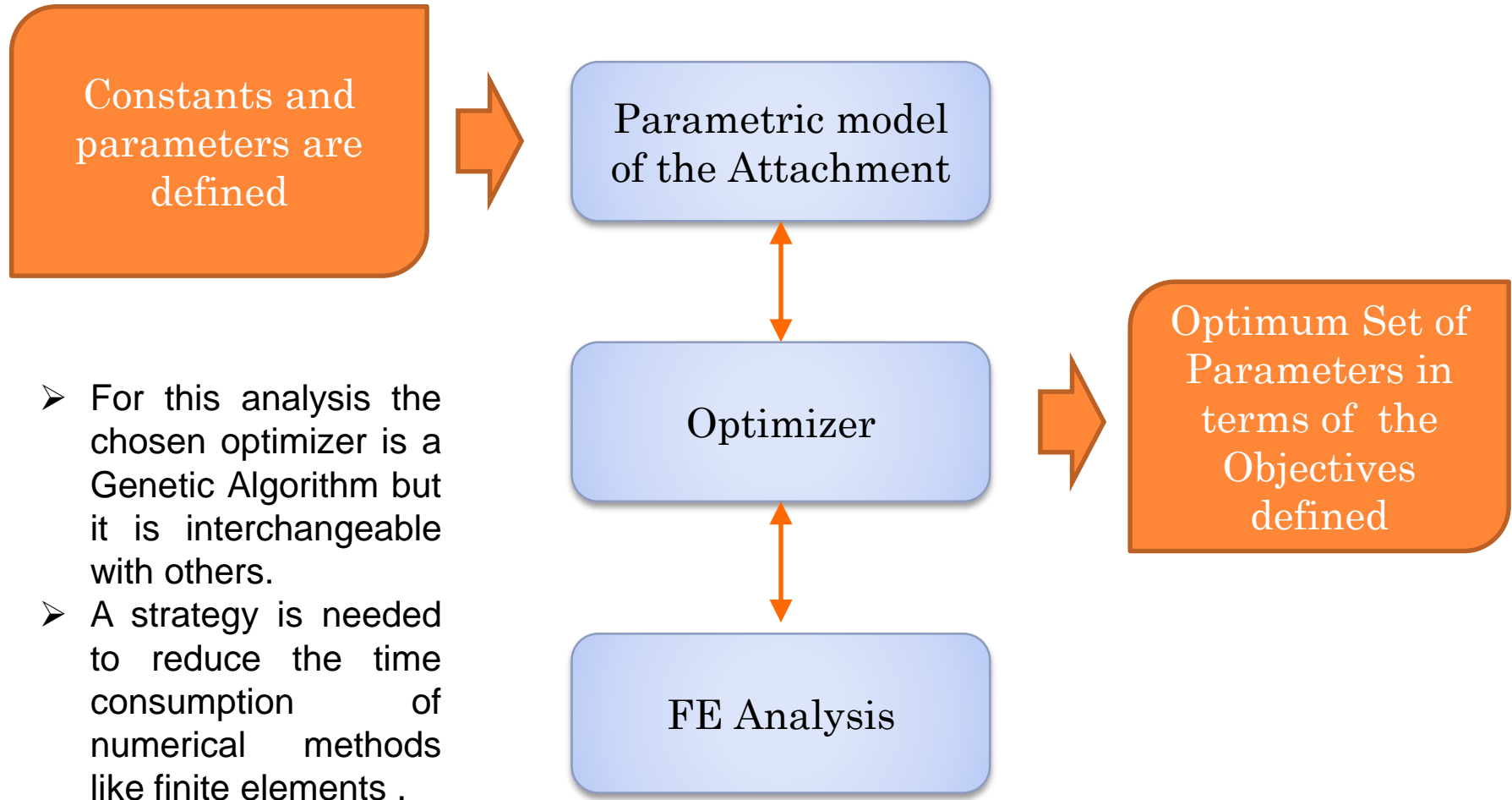
# INTRODUCTION



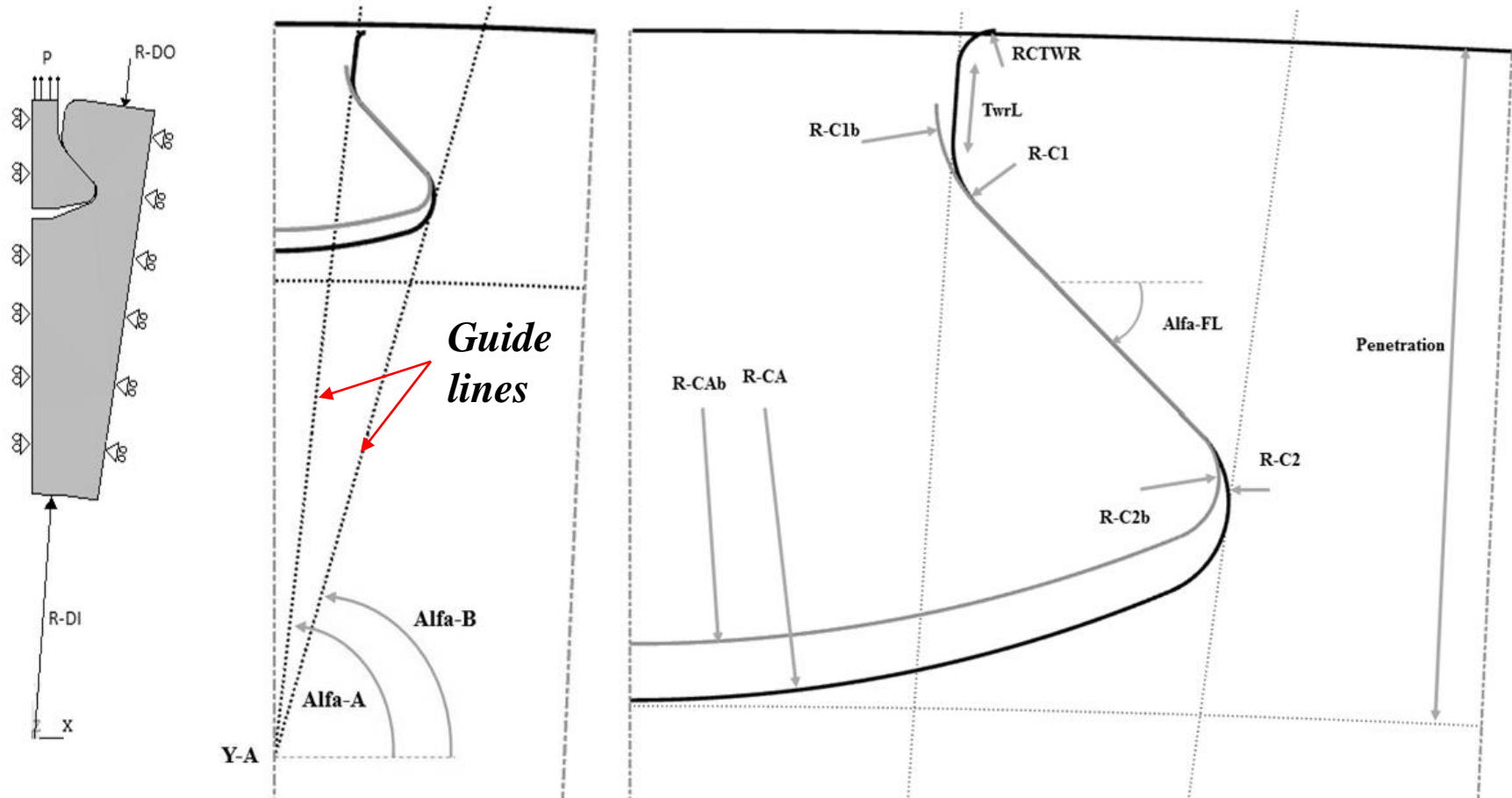
- ❑ The aim is to
  - Apply some complex profiles and different dimensions
  - Respond to “what ifs”
  - Decrease the high cost analysis
  - Exploit the material strength
  - Provide robust solutions
- ❑ The Strategies are:
  - Defining the parametric attachment model.
  - Applying Meta model in Optimization
  - Minimizing the stress state in critical areas.



# Process Outline



# Parametric description - Dovetail



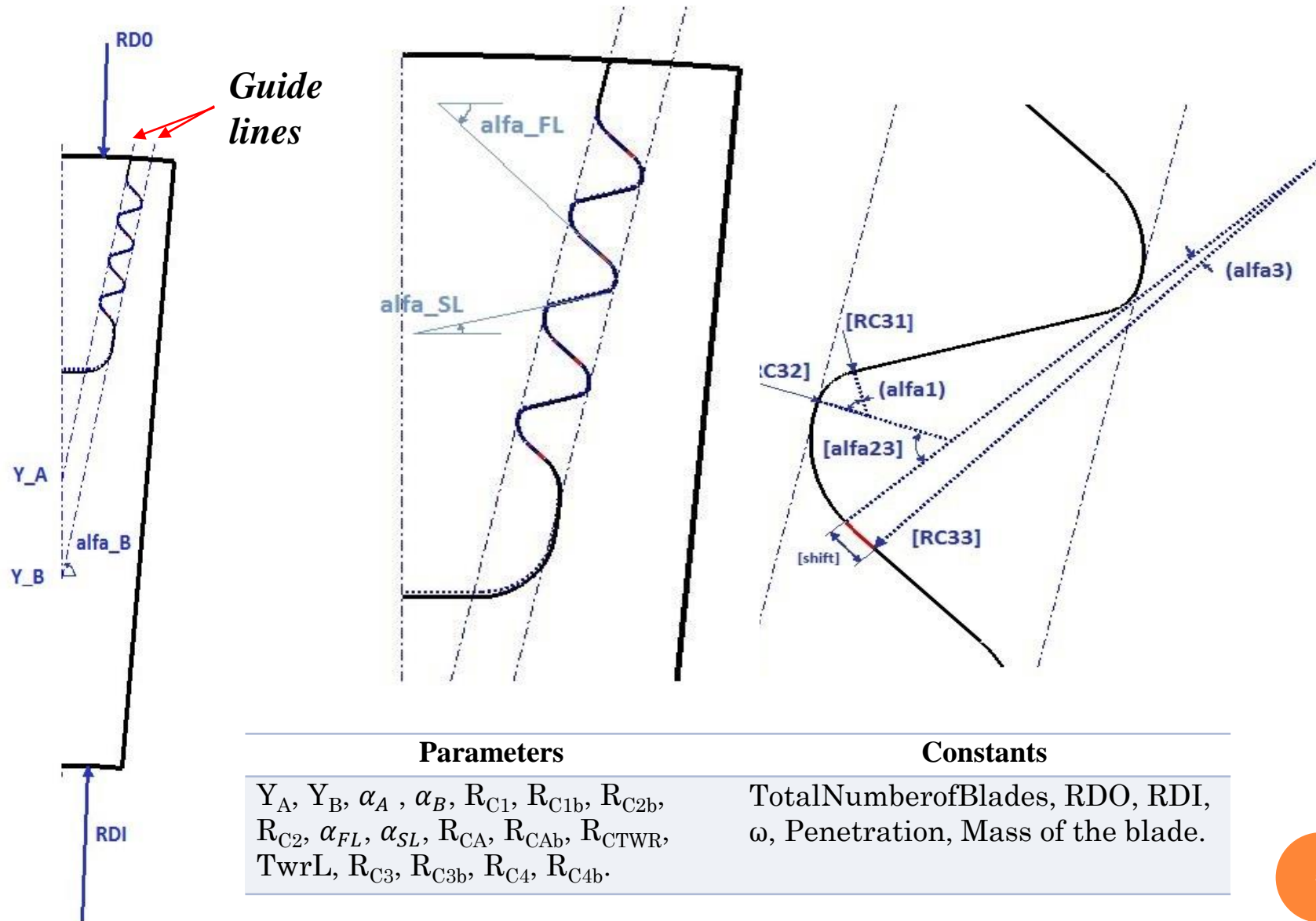
## Parameters

$Y_A, Y_B, \alpha_A, \alpha_B, R_{C1}, R_{C1b}, R_{C2b}, R_{C2}, \alpha_{FL}, R_{CA}, R_{CAb}, R_{CTWR}, TwrL, R_{C1b},$

## Constants

TotalNumberOfBlades,  $R_{DO}, R_{DI}, \omega,$   
Penetration, Mass of the blade.

# PARAMETRIC GEOMETRY – Firtree



## DIMENSION OF THE PROBLEM

### ○ Dovetail

Number of Parameters: 10

The minimum number of divisions for every parameter range: 50

The minimum time for FE evaluation of every trial with a common PC: 15 seconds

Total time for evaluating all possible Geometries:

$$10^{50} \times 15 = 1.5e51 \text{ seconds}$$

$$= 1.7e46 \text{ days}$$

$$= 4.7e43 \text{ Years}$$

### ○ Firtree (with 4 teeth)

Number of Parameters: 19

The minimum number of divisions for every parameter range: 50

The minimum time for FE evaluation of every trial with a common PC: 30 seconds

Total time for evaluating all possible Geometries:

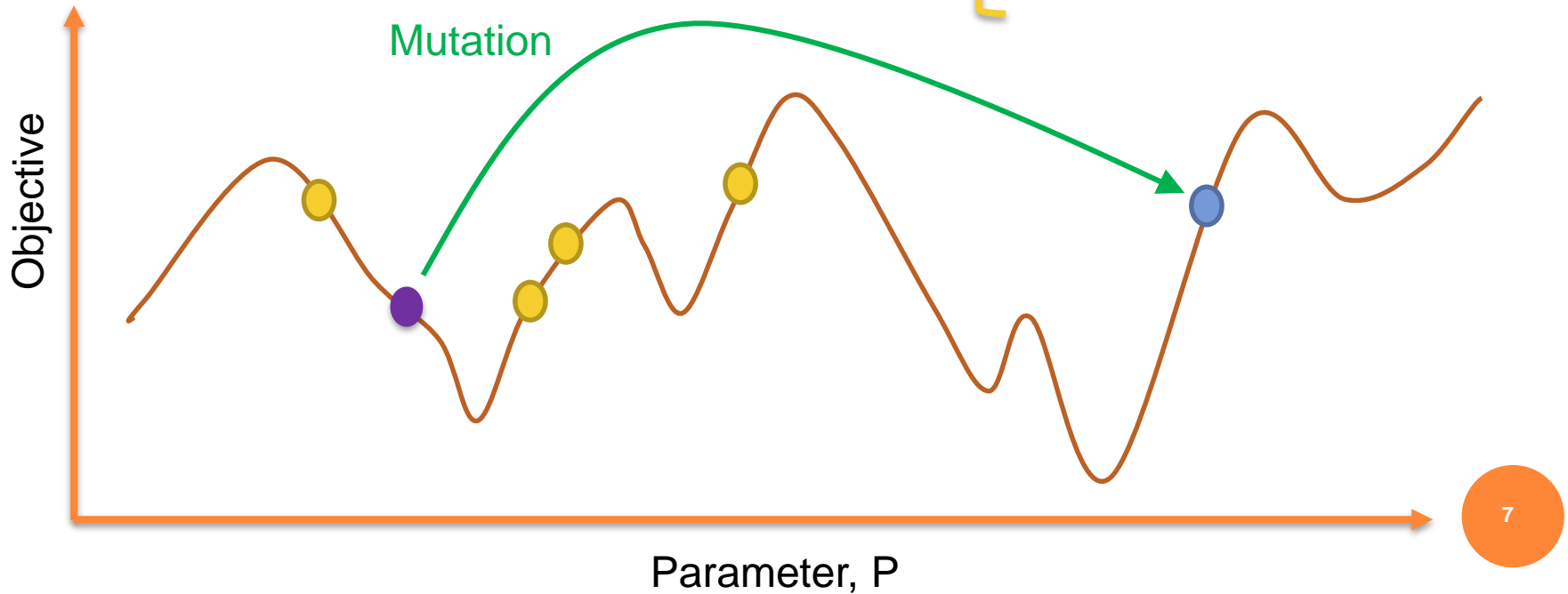
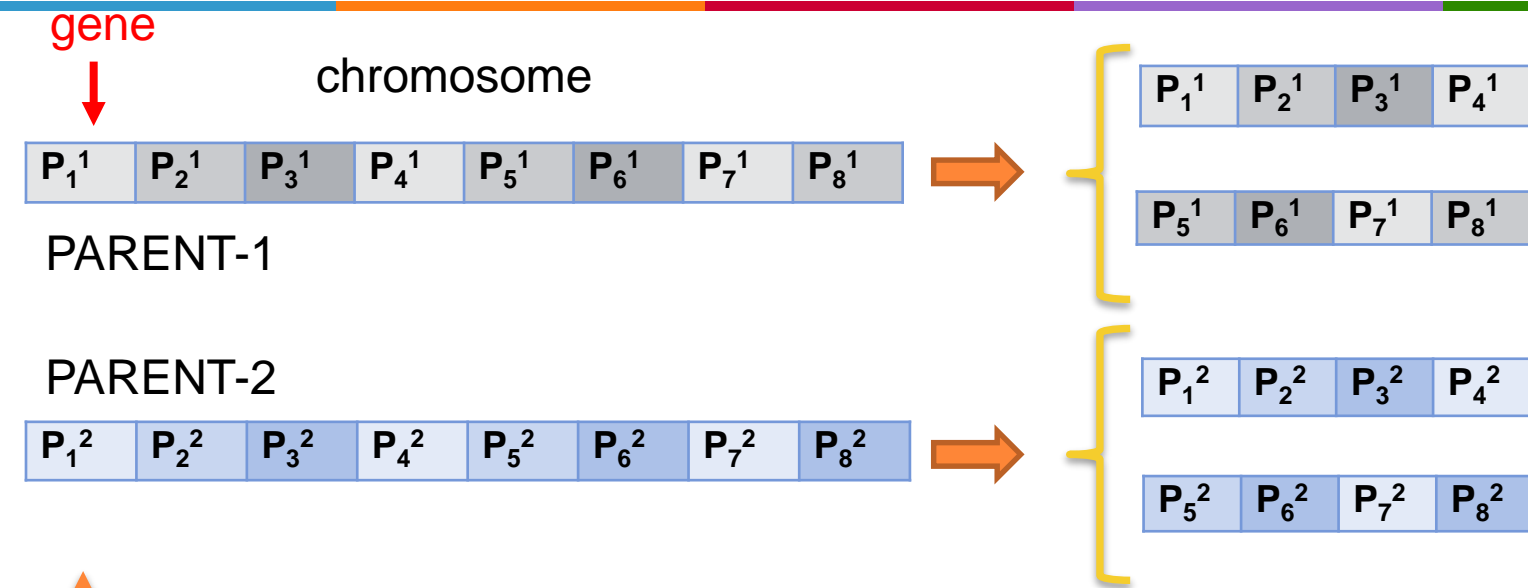
$$19^{50} \times 30 = 2.6e65 \text{ seconds}$$

$$= 3e60 \text{ days}$$

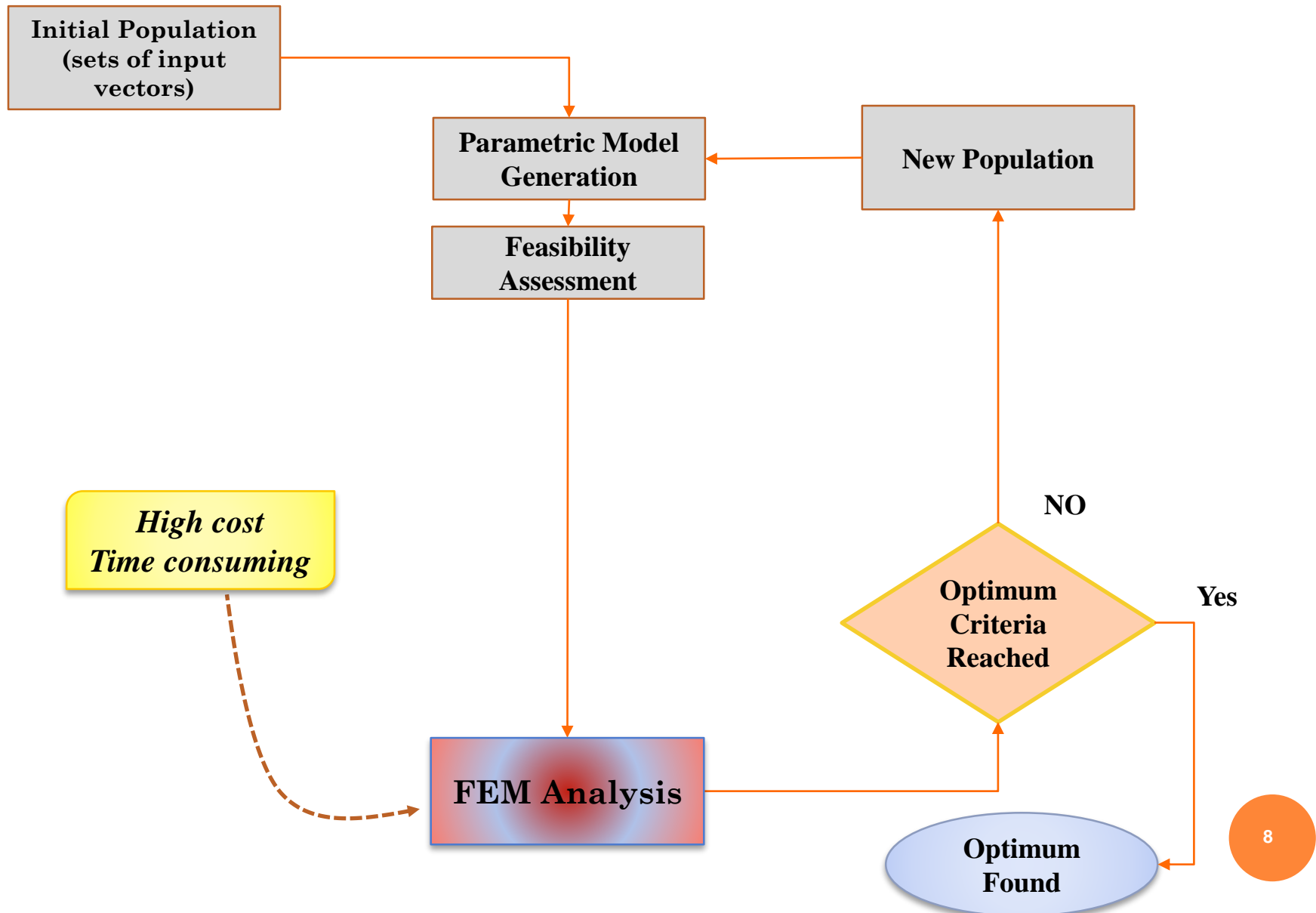
$$= 8.24e57 \text{ Years}$$

How old is the universe: **14e9 Years**

# GENETIC ALGORITHM



# OPTIMIZATION METHOD – GENETIC ALGORITHM

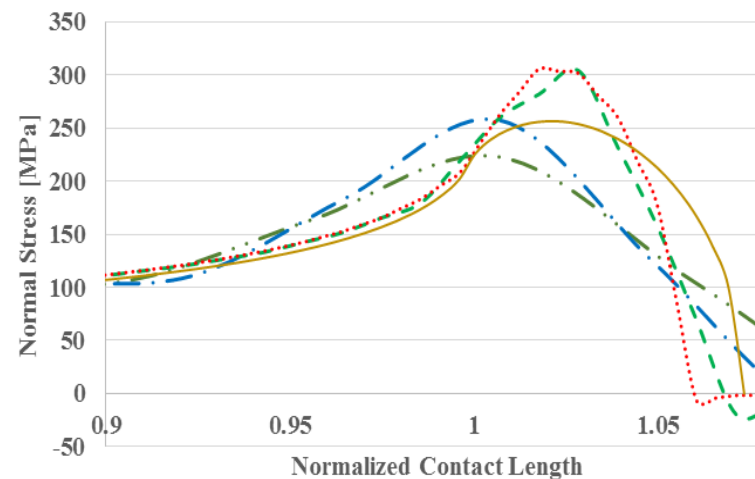
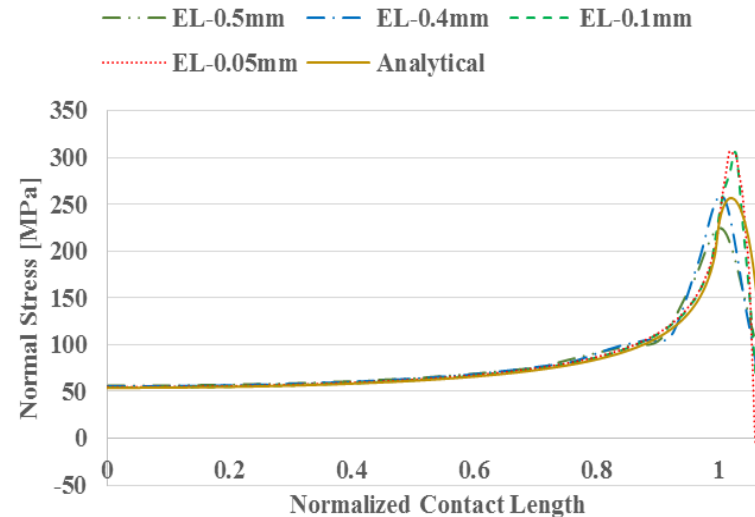
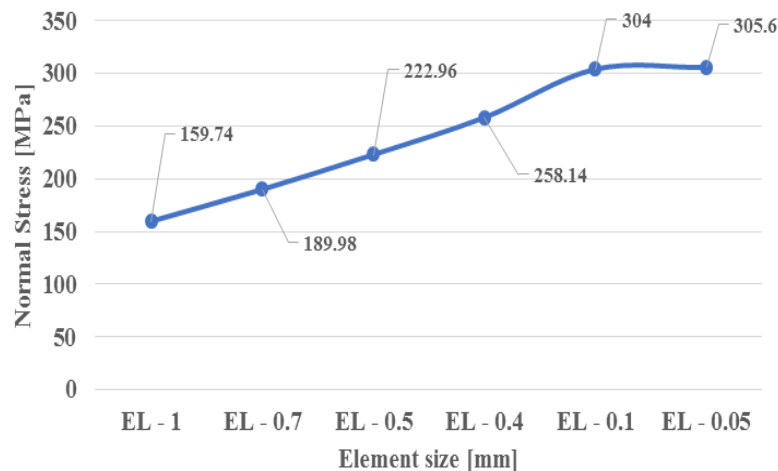
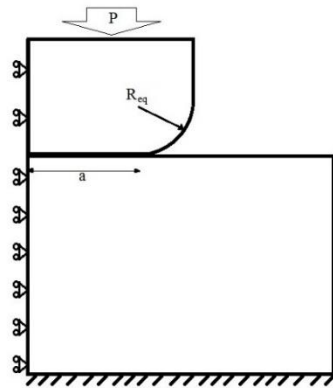




# BENCHMARK FOR MESH CONVERGENCE

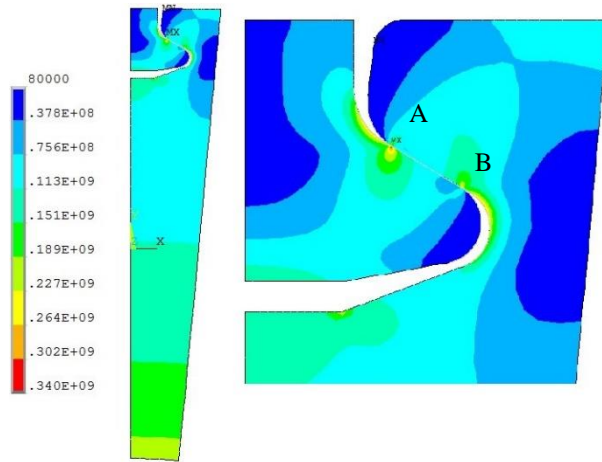
A punch type contact was simulated as a benchmark, to check the mesh convergence and also comparing FE solution with an analytical solution of contact.

The mesh size is kept constant during the optimization procedure

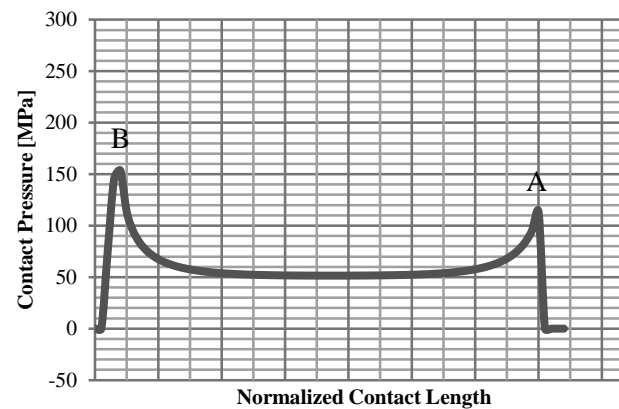
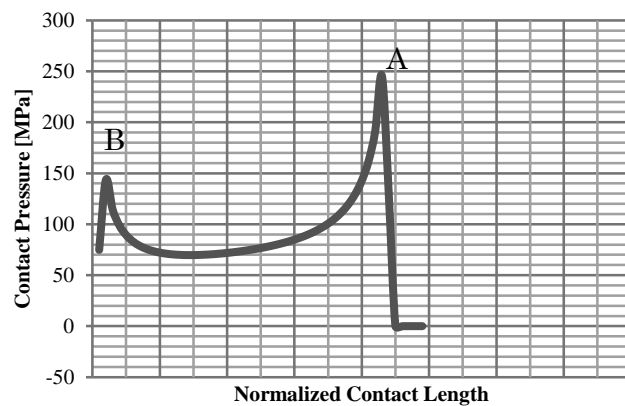
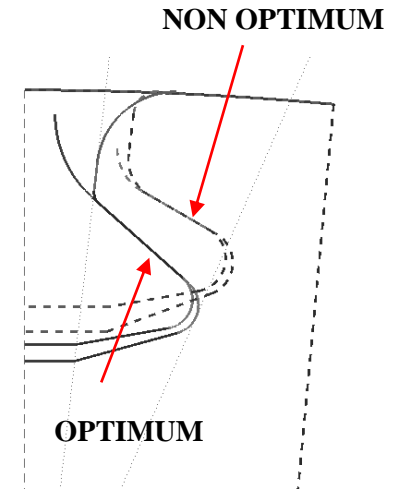
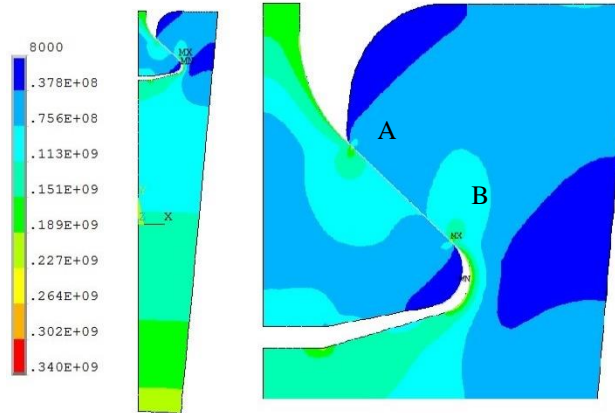


# GA OPTIMUM VS. NON-OPTIMUM GEOMETRY (OBJECTIVE: EQV STRESS)

**NON-OPT GEOM:**  
**Max  $\sigma_{EQV}$ =336 MPa**

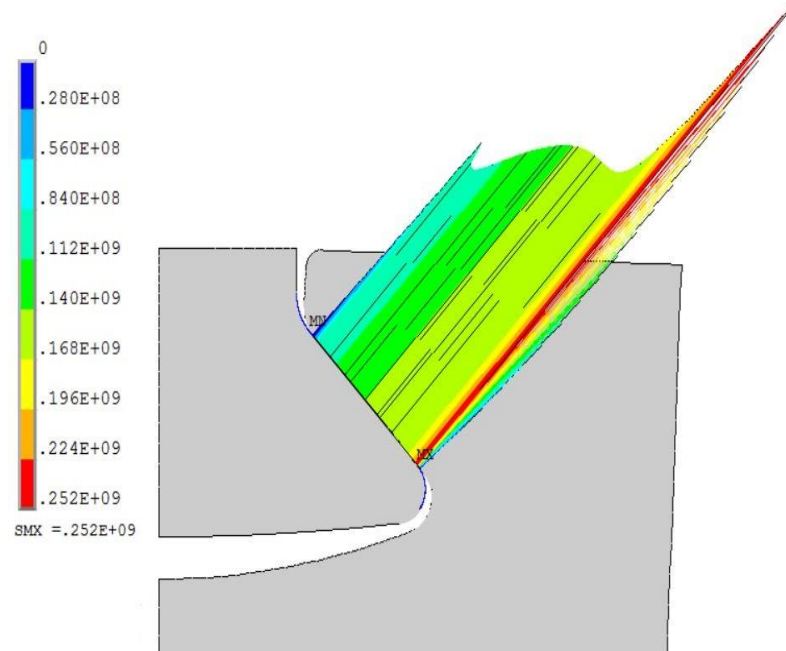
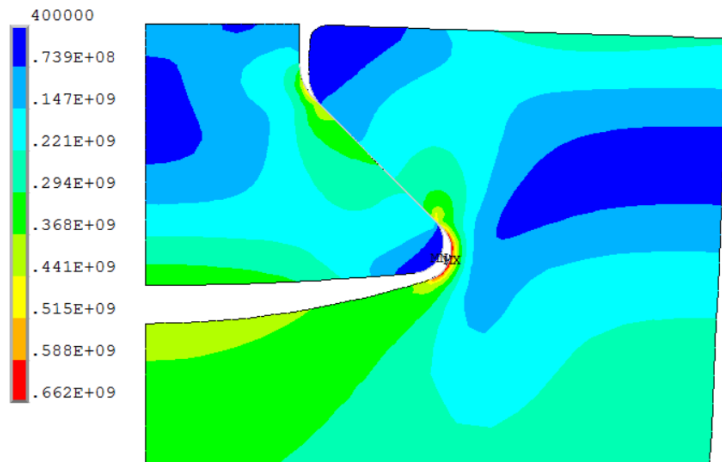


**OPTIMUM GEOM:**  
**Max  $\sigma_{EQV}$ =207 MPa**

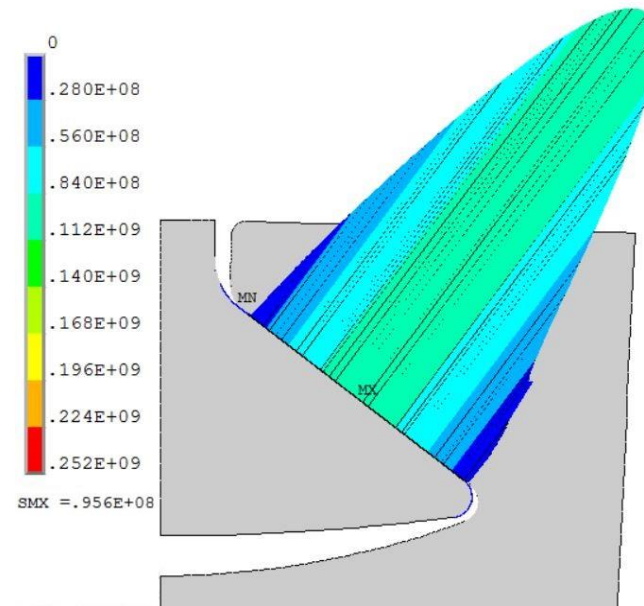
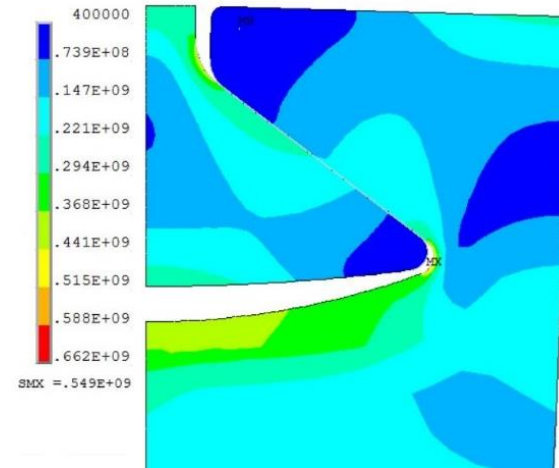


# OBJECTIVE FUNCTION: CONTACT PRESSURE (CASE II)

NON OPTIMUM



OPTIMUM



# REDUCING COMPUTATIONAL COST

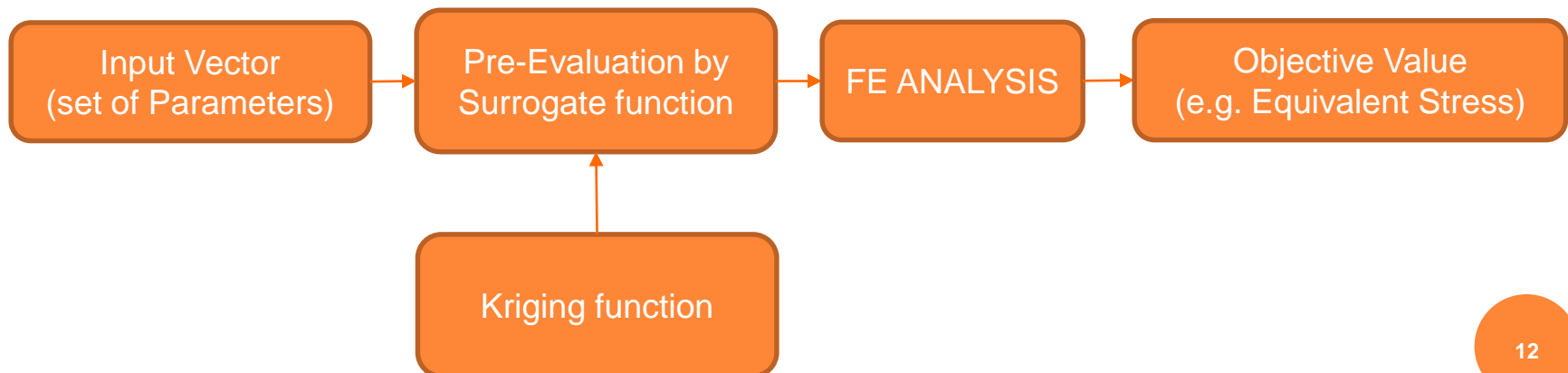
## Direct FE Analysis



## Surrogate Model (Meta-Model)

$$y = f(x) \quad \text{Where} \quad x: V_{Input} \quad \text{and} \quad y: \sigma_{EQV}$$

## Surrogate Function – FE Analysis



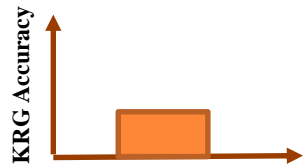
# SURROGATION

Iteration N

Iteration N+1

Surrogate Response

O1	X1	Y1
O2	X2	Y2
O3	X3	Y3
O4	X4	Y4
O5	X5	Y5
O6	X6	Y6

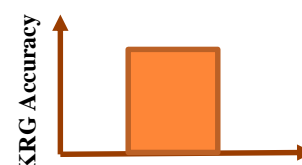


FEM Analysis

O1	X1	F1
O3	X3	F3
O6	X6	F6

Surrogate Response

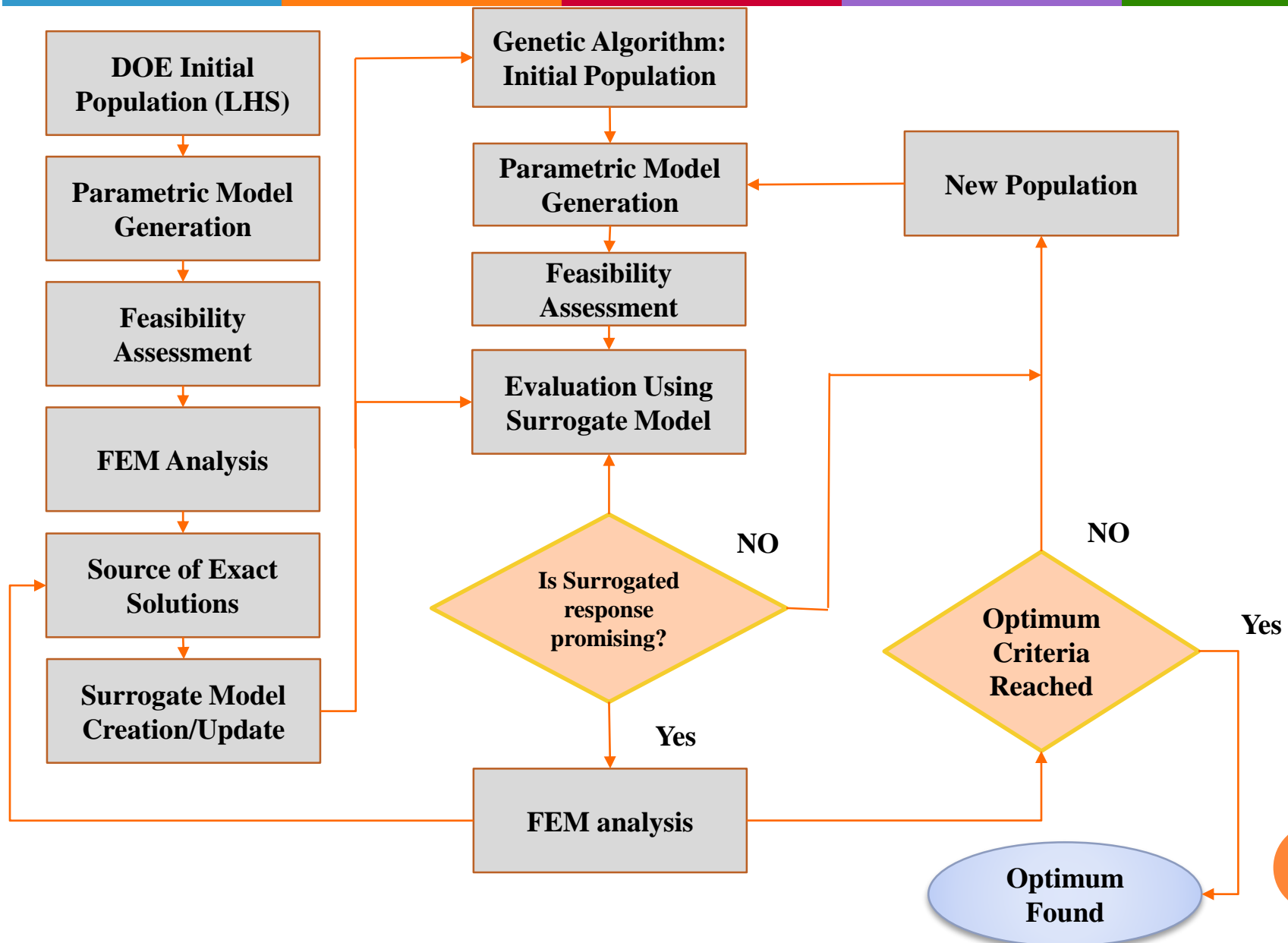
O1	X1	Y1
O2	X2	Y2
O3	X3	Y3
O4	X4	Y4
O5	X5	Y5
O6	X6	Y6



FEM Analysis

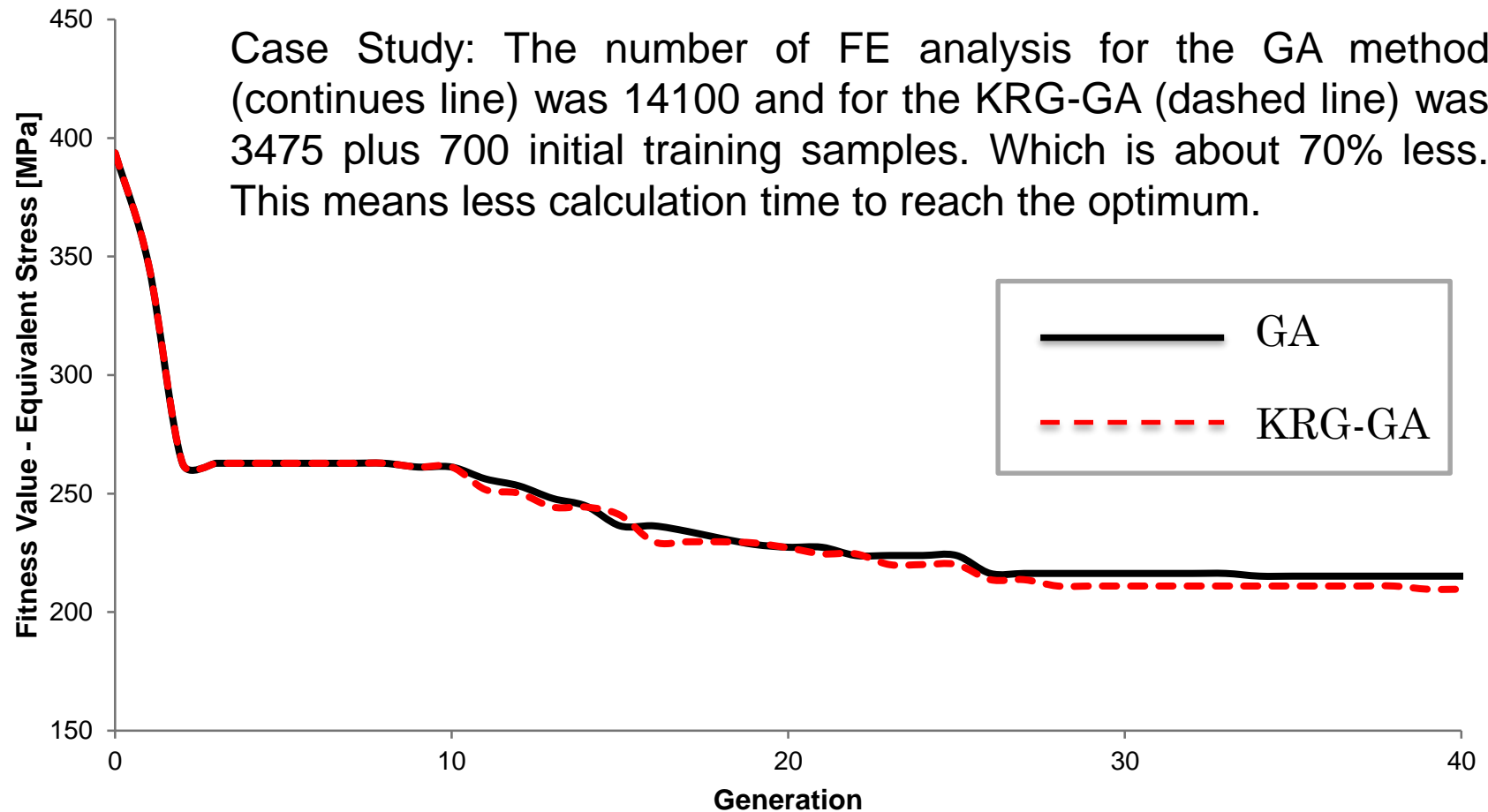
O2	X2	F2
O5	X5	F5

# KRG-GA OPTIMIZATION FLOWCHART



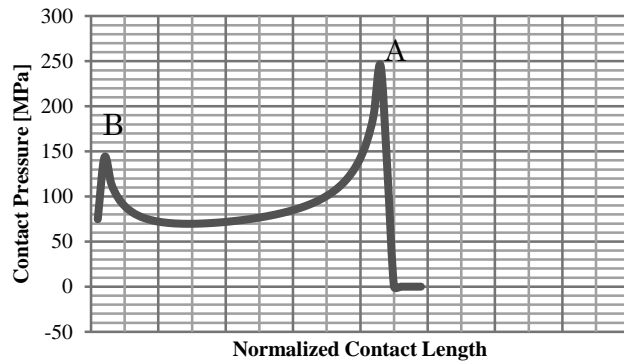
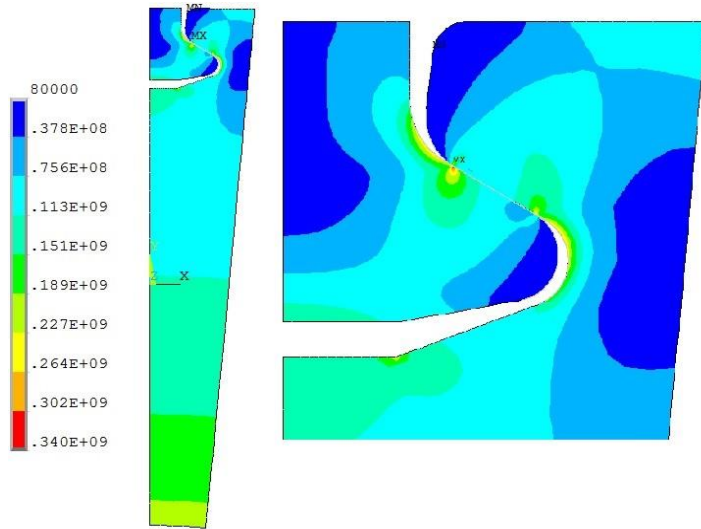
# GA vs KRG-GA OPTIMIZATION

Case Study: The number of FE analysis for the GA method (continues line) was 14100 and for the KRG-GA (dashed line) was 3475 plus 700 initial training samples. Which is about 70% less. This means less calculation time to reach the optimum.

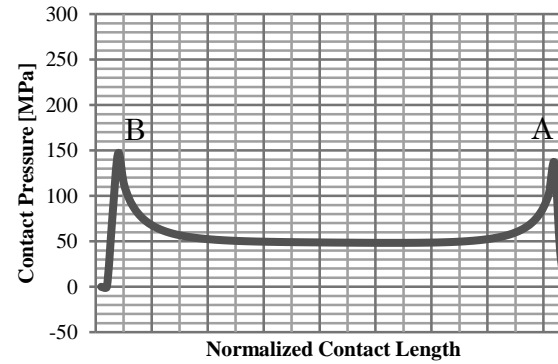
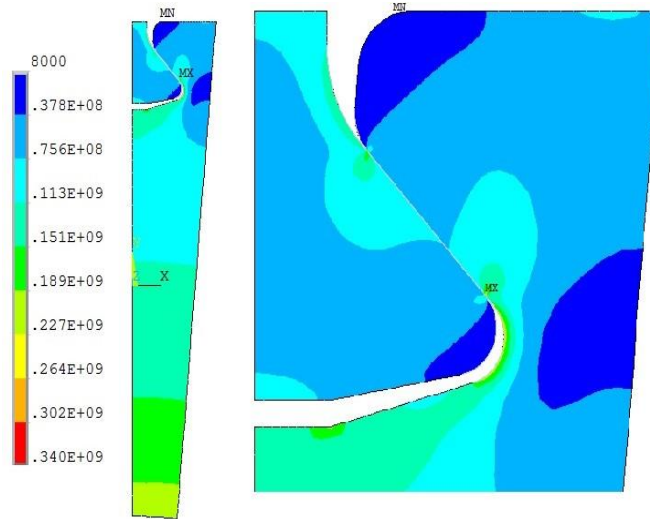


# KRG-GA OPTIMUM VS NON-OPTIMUM GEOMETRY

**NON-OPT GEOM:**  
**Max  $\sigma_{EQV}$ =339 MPa**

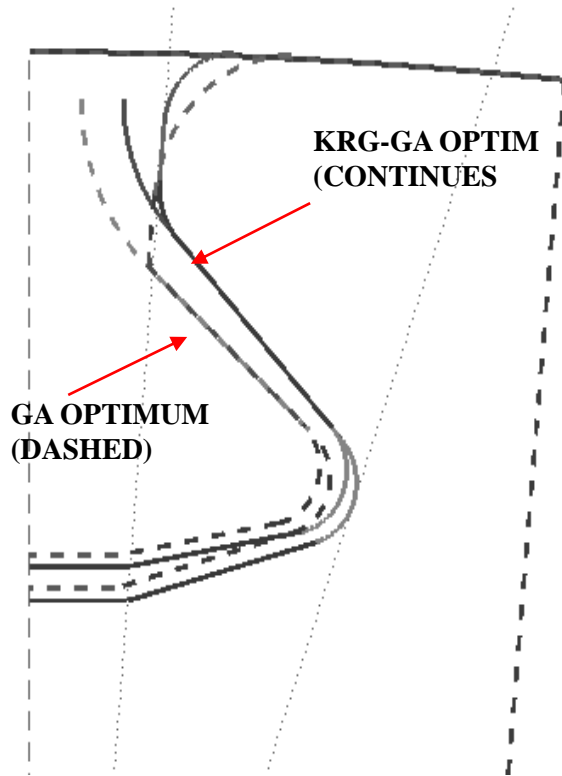


**OPTIMUM GEOM:**  
**Max  $\sigma_{EQV}$ =206 MPa**



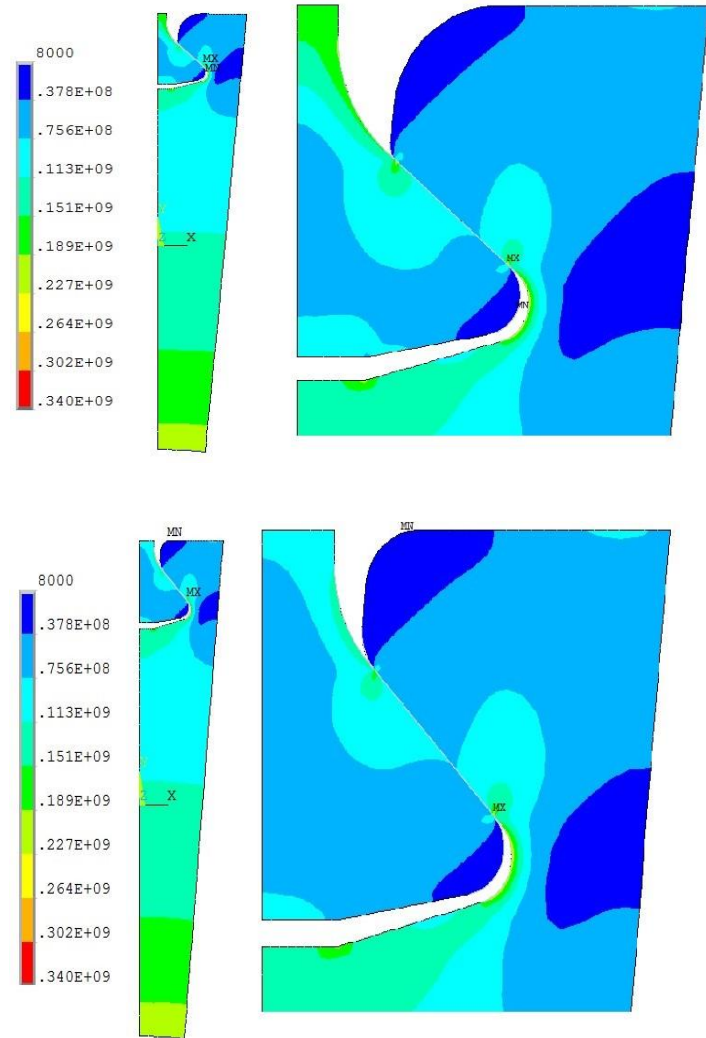


# KRG-GA OPTIMUM VS. GA OPTIMUM

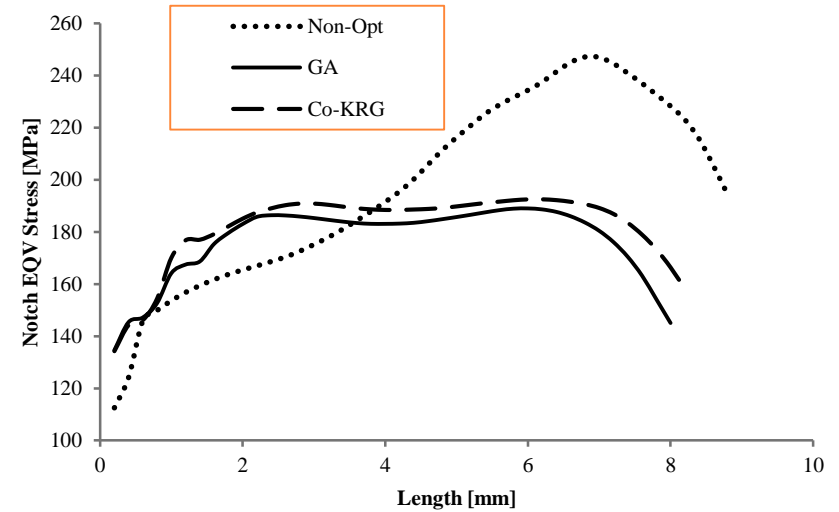
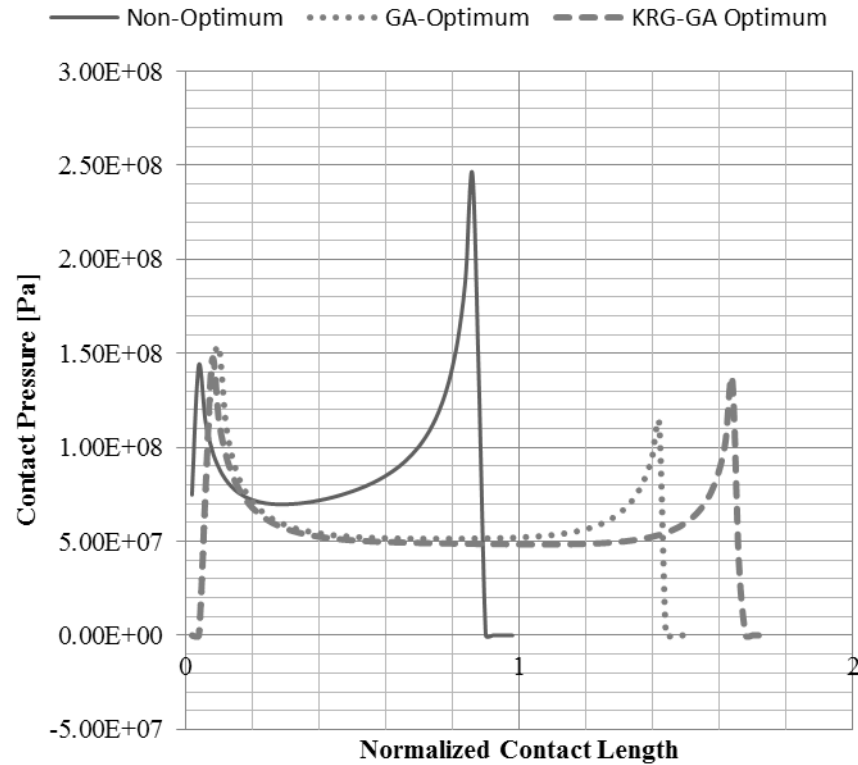


**GA  
OPTIMUM  
GEOMETRY**  
Max  
 $\sigma_{\text{EQV}}=207$   
(MPa)

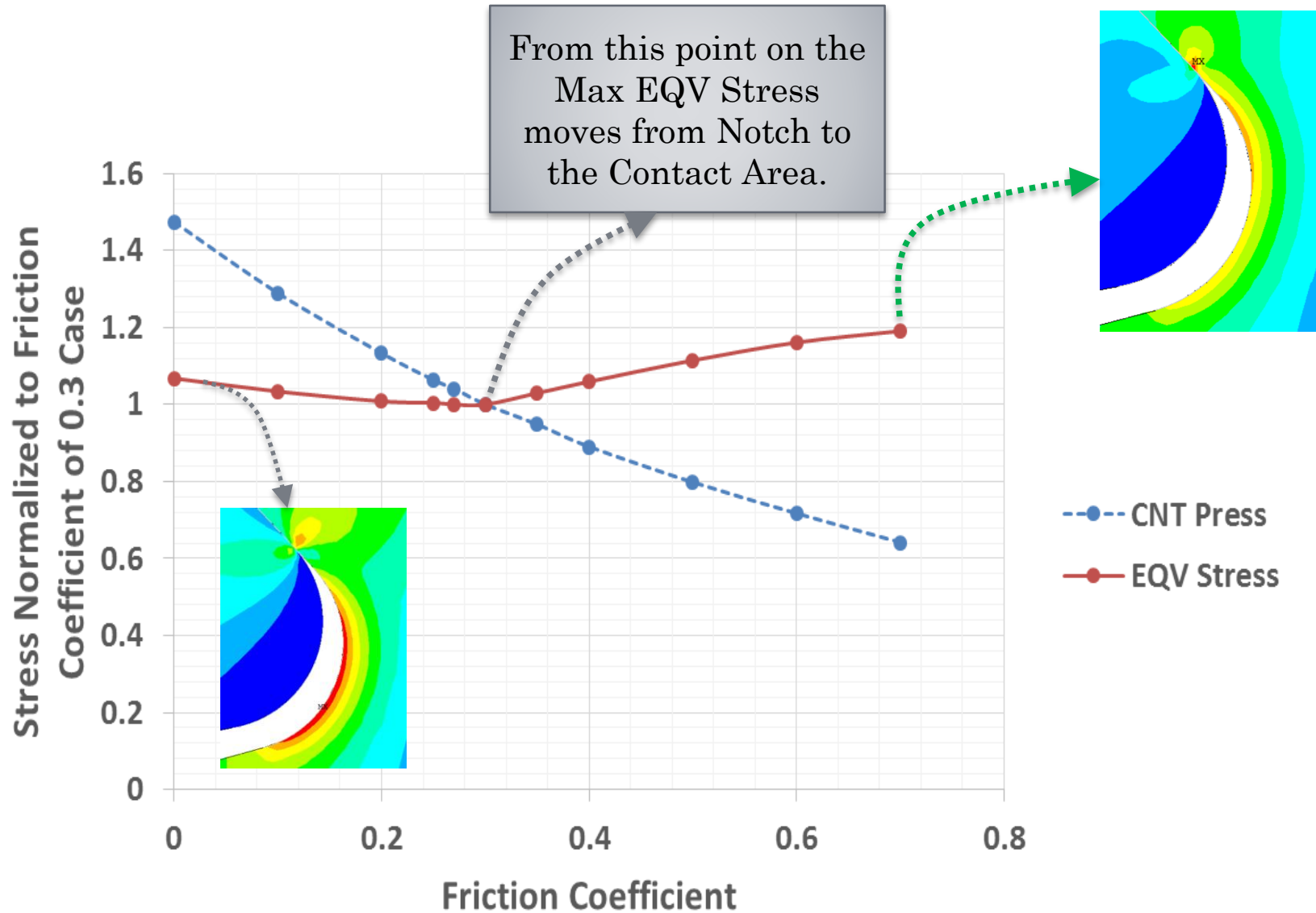
**KRG-GA  
OPTIMUM  
GEOMETRY**  
Max  
 $\sigma_{\text{EQV}}=206$   
(MPa)



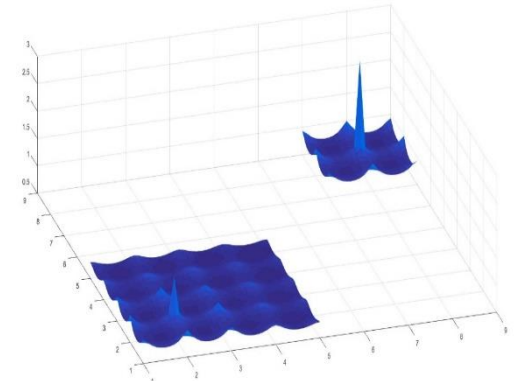
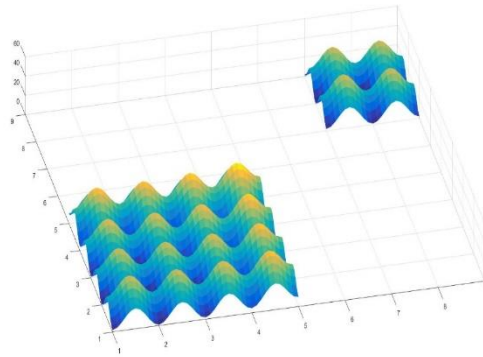
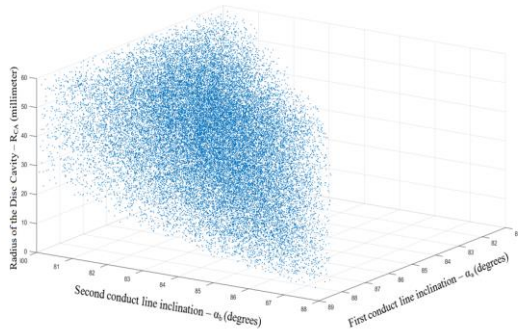
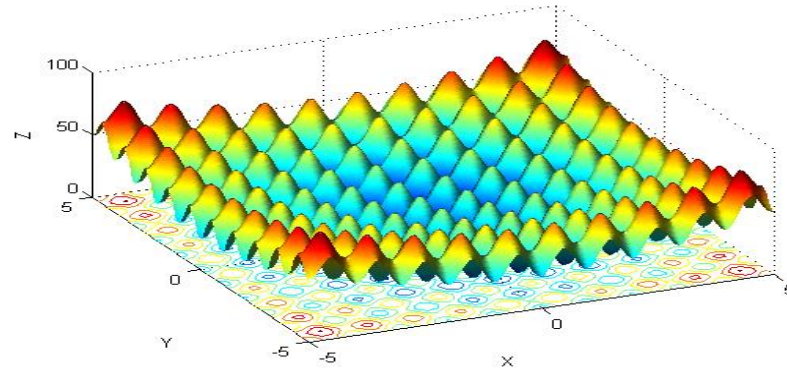
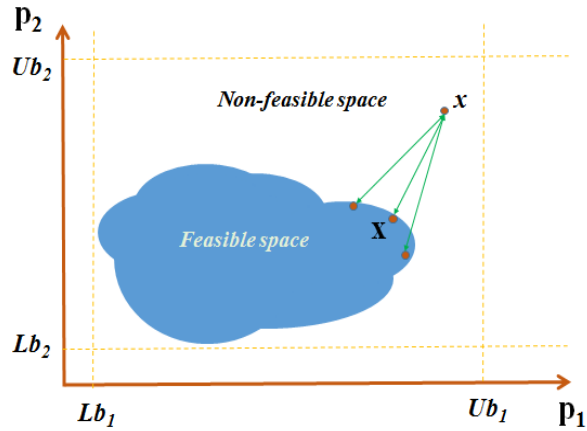
# CONTACT PRESSURE AND NOTCH EQUIVALENT STRESS



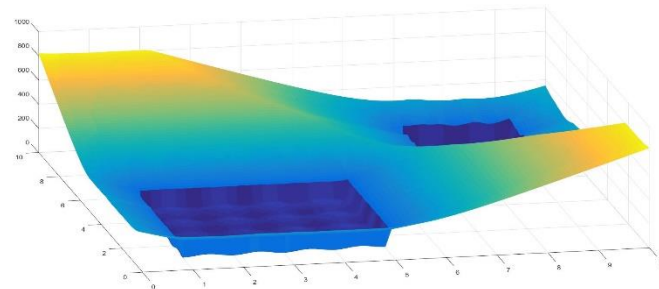
# FRICTION COEFFICIENT EFFECT



# LHS-BASED ADAPTIVE PENALTY - FEASIBILITY

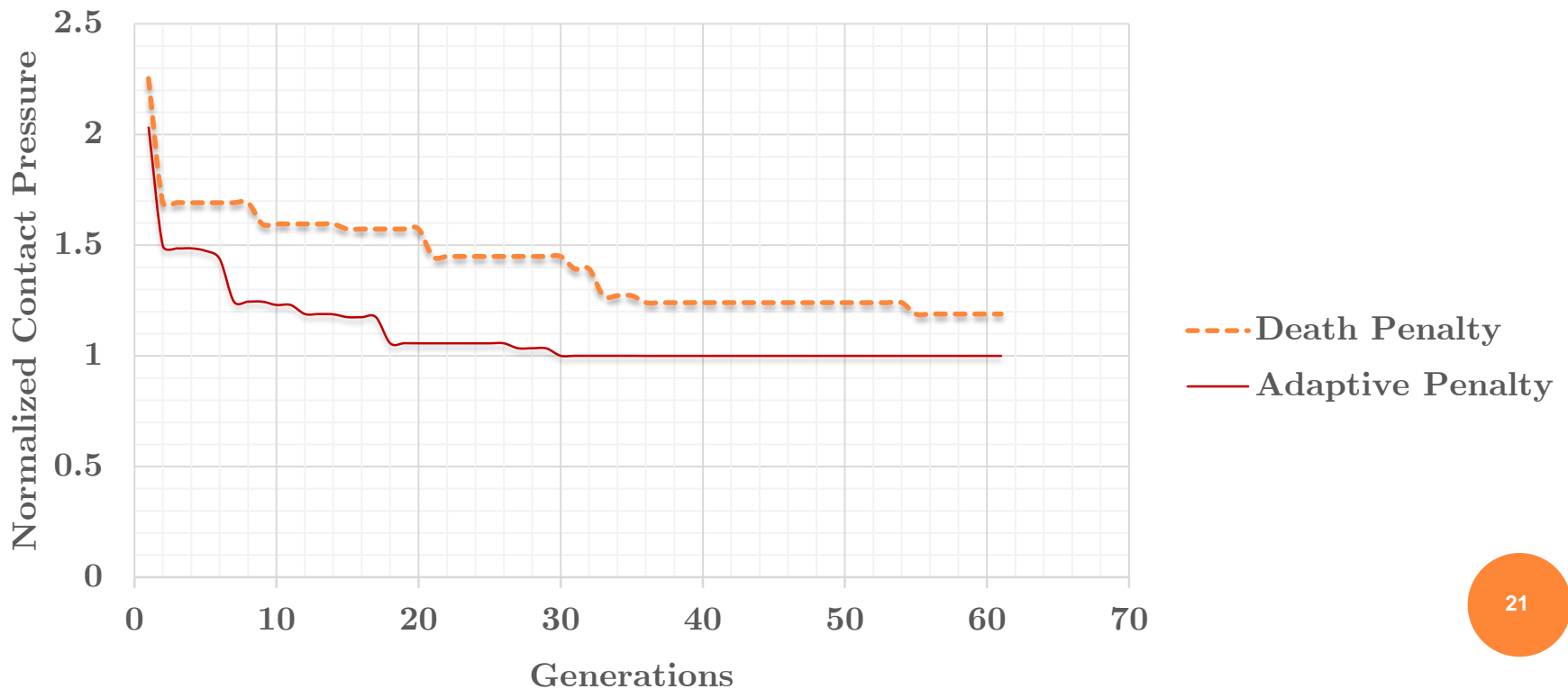


$$\phi_P(x) = \begin{cases} \phi(x) & , \text{if } x \text{ is feasible.} \\ C_f \left( \sum_{i=1}^{NP} \left( \frac{x_i - X_i}{Ub_i - Lb_i} \right)^2 + 1 \right) & , \text{if } x \text{ is not feasible.} \end{cases}$$

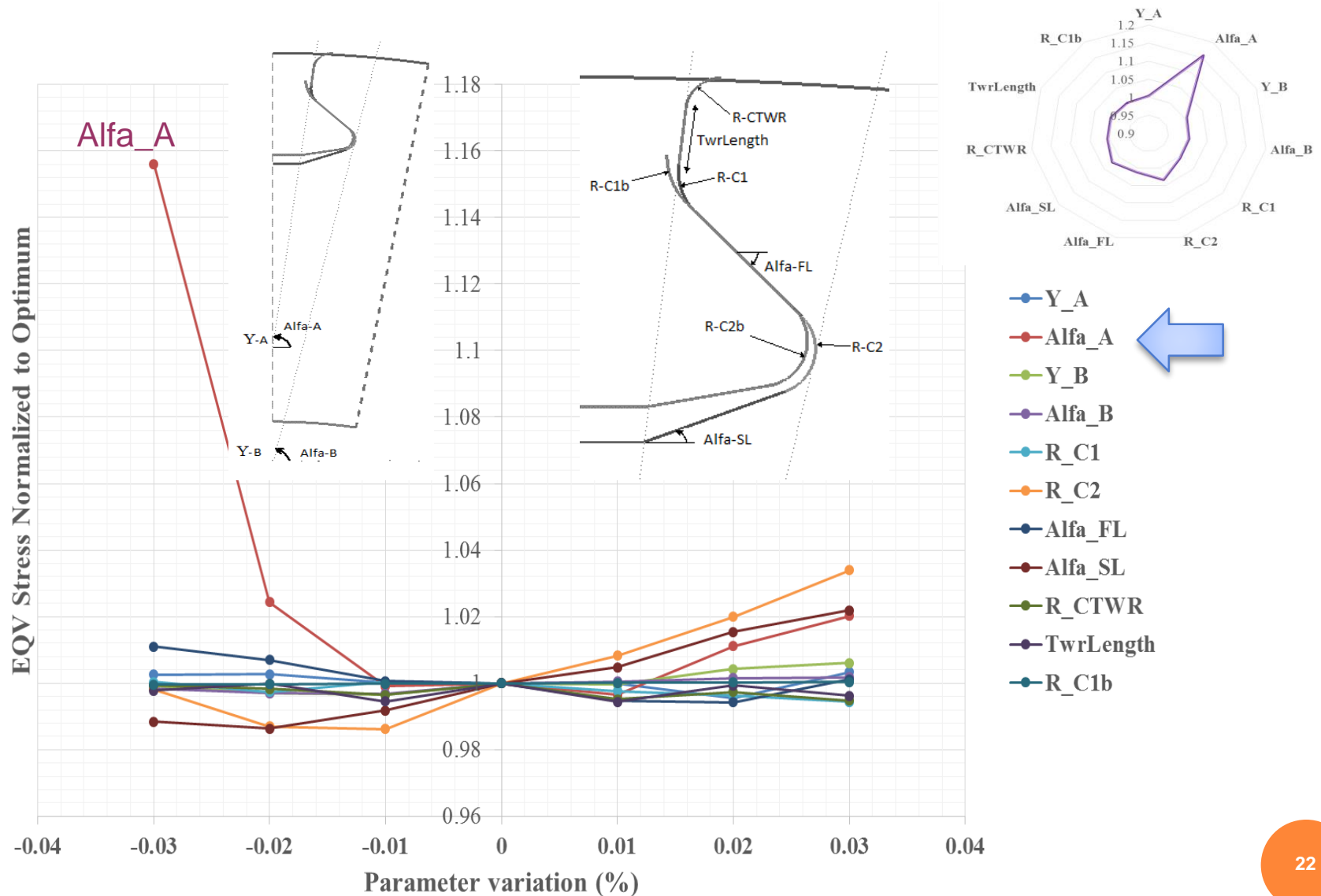


# ADAPTIVE PENALTY – EFFICIENT & EFFECTIVE

$$\phi_P(x) = \begin{cases} \phi(x) & , \text{if } x \text{ is feasible.} \\ C_f \left( \sum_{i=1}^{NP} \left( \frac{x_i - X_i}{Ub_i - Lb_i} \right)^2 + 1 \right) & , \text{if } x \text{ is not feasible.} \end{cases}$$



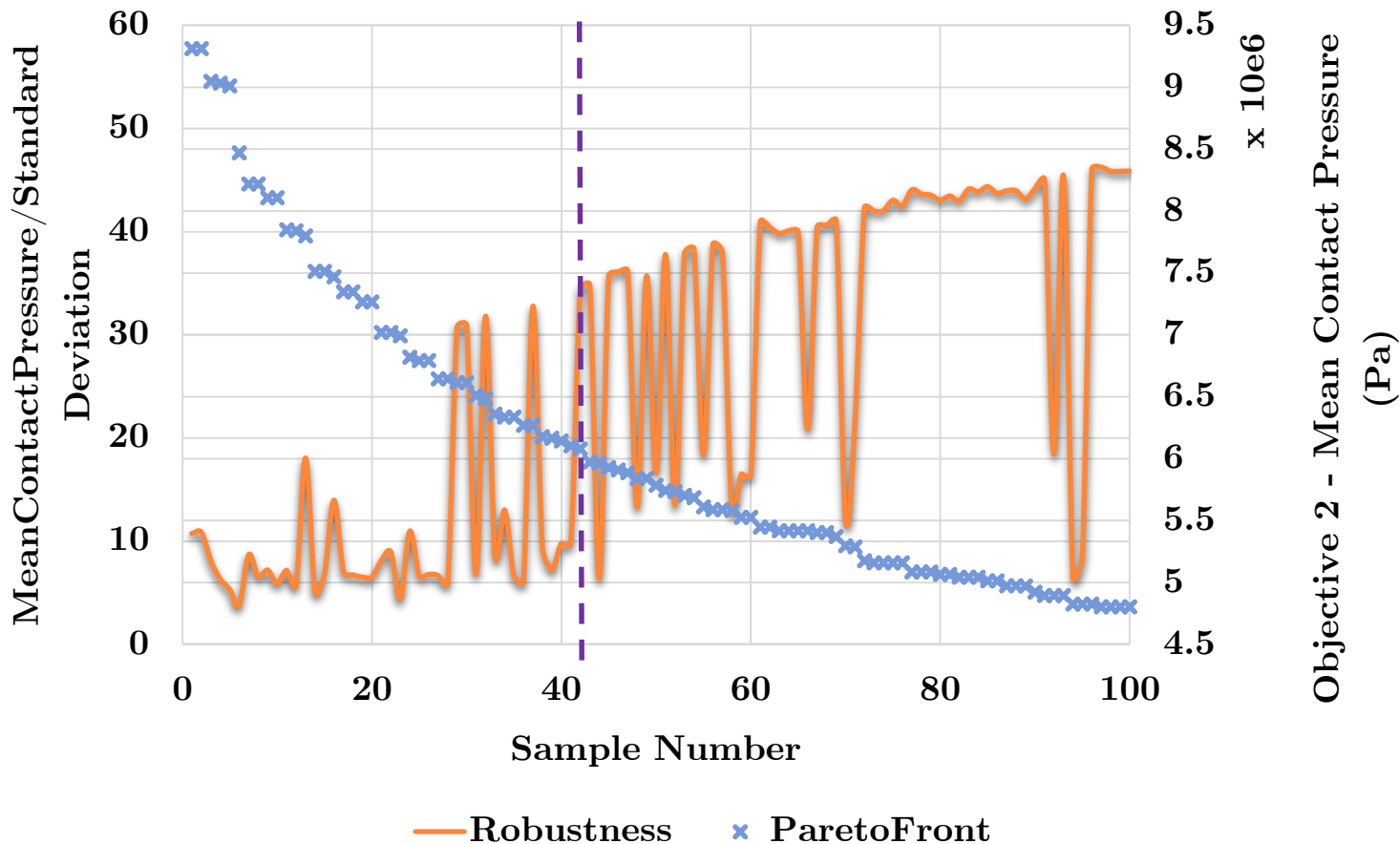
# LOCAL SENSITIVITY ANALYSIS (NOT A GOOD IDEA!)



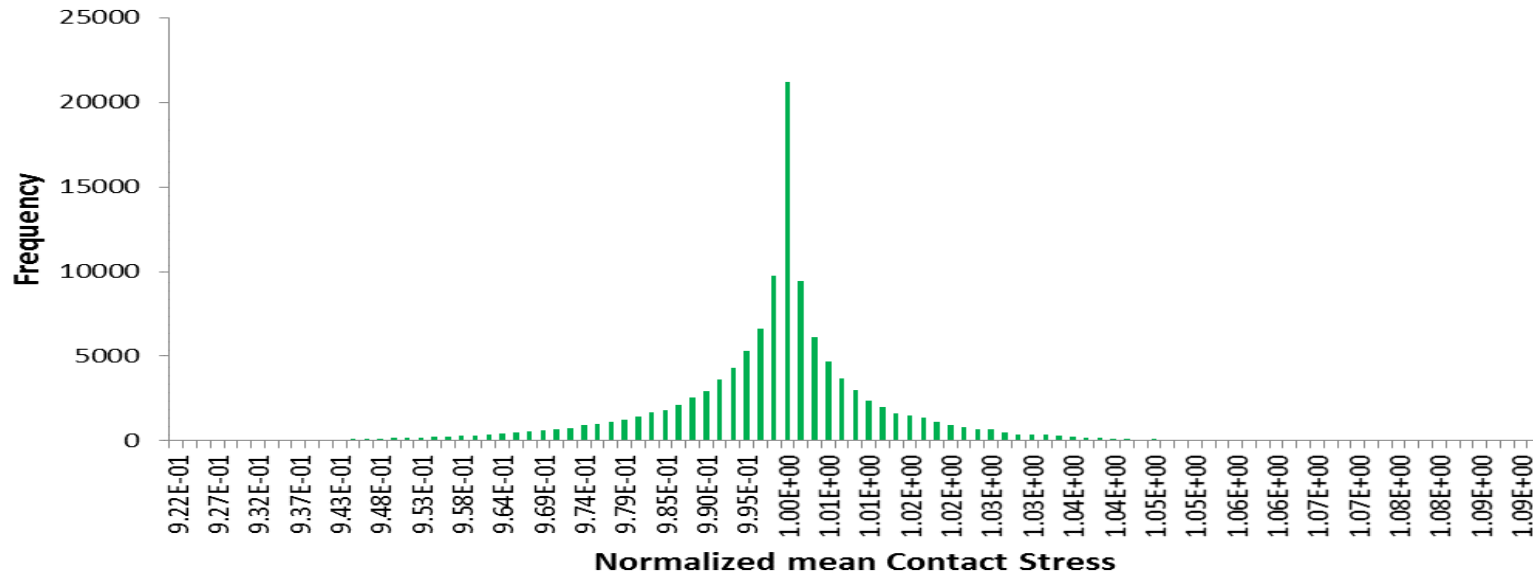
# ROBUSTNESS (GLOBAL SENSITIVITY)

signal to noise (S/N) ratio

$$S = \sqrt{\frac{1}{N} \sum_{i=1}^N (CMP_i - \mu)^2}$$



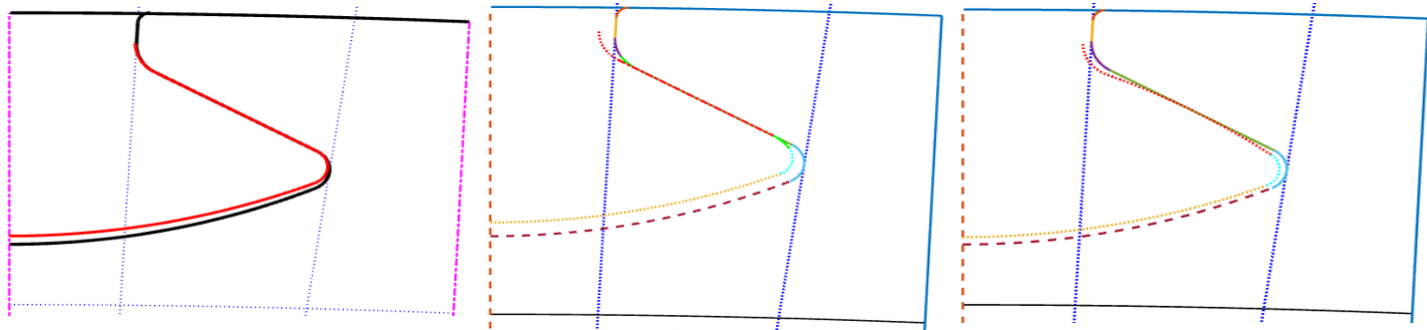
signal to noise (S/N) ratio



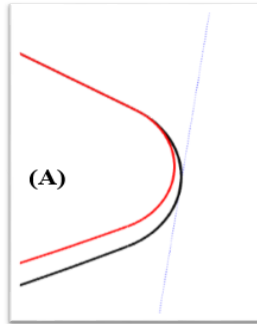
	MPS1 (normalized)	Contact Mean Pressure (Mpa)
Standard Deviation	0.026	1.7
Mean	0.583	60.46
S/N	22.42	35.56



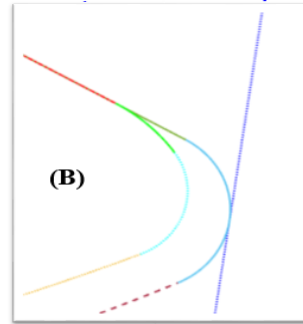
# DIFFERENT CONTACT TOPOLOGIES



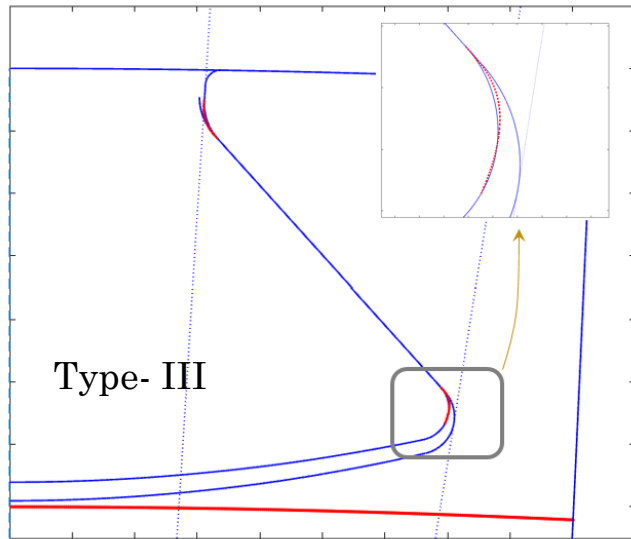
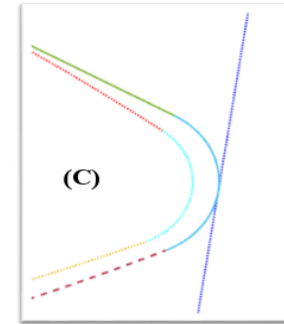
Type-I



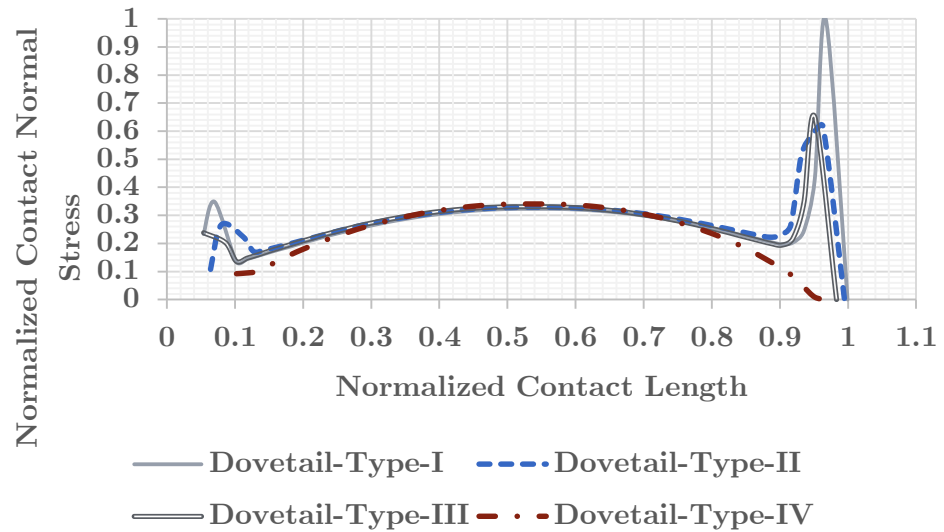
Type- II



Type- IV



Type- III



# CONCLUSION & ACHIEVEMENTS

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- *The Parametric model showed a good flexibility to provide different shapes of the attachment.*
- *The feasibility check in-house code could filter out the non feasible geometries before proceeding to the objective analyzer with a high reliability.*
- *An optimizer based on Genetic Algorithm has been developed to find an optimum geometry minimizing the objectives.*
- *To reduce the time of the optimization a Meta model was employed as an estimator prior to high fidelity but time consuming FE analysis.*
- *The proposed Adoptive Penalty method based on LHS was efficient and effective which showed faster convergence in optimization (up to 40%).*
- *The global sensitivity analysis was performed applying the Meta model.*