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# **SYSTEMS HEALTH MANAGEMENT** *Framework and Applications*

## Subjects

#### 1) FUNDAMENTALS

#### 1.1: Background and objectives

#### 1.1.1: General considerations

- 1.1.2: Paradigm shift
- 1.1.3: Application areas
- 1.1.4: Summary of benefits

#### 1.2: Definitions

- 1.2.1: Basic definitions
- 1.2.2: Fault management definitions

## 1.3: Functions and requirements

- 1.3.1: SHM functional capabilities
- 1.3.2: Systems health management requirements

## **1.4: Reference architecture**

1.4.1: Integrated approach to CBM/PHM design

1.4.2: Health management logic diagram

#### **1.5: Enabling technologies**

- 1.5.1: Summary of enabling technologies
- 1.5.2: SHM significant issues
- 1.5.3: Modeling framework
- 1.5.4: Prognostic algorithms approaches
- 1.5.5: Physics of failure

## 2) SENSING AND DATA PROCESSING

## 2.1: Transducing principles

- 2.1.1: Measurements
- 2.1.2: Validation

#### 2.2: Sensors placement

2.2.1: Requirements

#### 2.3: Virtual sensors

- 2.3.1: Definition
- 2.3.2: Example

#### 2.4: Smart sensors

2.4.1: Objectives

#### 2.5: Data processing

- 2.5.1: Requirements
- 2.5.2: Validation
- 2.5.3: Features selection and extraction
- 2.5.4: Data fusion
- 2.5.5: Signals characterization
- 2.5.6: Data rate

#### 2.6: Use cases of signals analysis for health assessment

2.6.1: Effect of a fault on vibration signature

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- 2.6.2: Gear health analysis
- 2.6.3: Bearings health analysis
- 2.6.4: Lubricant health analysis

#### 3) PROGNOSTICS AND HEALTH MANAGEMENT

## 3.1: Framework

- 3.1.1: Definitions
- 3.1.2: Steps for developing a PHM system
- 3.1.3: FMECA
- 3.1.4: Elements of a PHM system
- 3.1.5: Applications

#### 3.2: Methodologies for fault diagnosis

- 3.2.1: Fault detection strategies
- 3.2.2: Feature vector
- 3.2.3: Data diagnostic methods
- 3.2.4: Fault classification
- 3.2.5: Model based reasoning
- 3.2.6: Case based reasoning
- 3.2.7: Dynamic case based reasoning
- 3.2.8: Rule based systems
- 3.2.9: Statistical change detection
- 3.2.10: Bayesian networks
- 3.2.11: Hidden Markov models
- 3.2.12: Multivariate statistical methods

#### 3.3: Methodologies for failure prognosis

- 3.3.1: Prediction framework
- 3.3.2: Model based prognostics
- 3.3.3: Data driven prognostics
- 3.3.4: Adaptive prognostics
- 3.3.5: Experience based prognostics

#### 3.4: Performance metrics

- 3.4.1: Diagnosis and prognosis requirements
- 3.4.2: Diagnosis performance metrics
- 3.4.3: Prognosis performance metrics
- 3.4.4: Effectiveness metrics

#### 3.5: Data mining

- 3.5.1: Definition
- 3.5.2: Tasks

#### 3.6: Use case: PHM applied to electro-hydraulic flight control actuators

- 3.6.1: Introduction
- 3.6.2: Methodology
- 3.6.3: Modeling and simulation
- 3.6.4: Faults diagnosis and failure prognosis

#### 3.7: Use case: PHM applied to electro-mechanical flight control actuators

- 3.7.1: EMA architecture
- 3.7.2: Signals analysis
- 3.7.3: Failure modes and their classification
- 3.7.4: Modeling and features identification
- 3.7.5: Prognostics









#### 4.1: Introduction to Integrated Vehicle Health Management

- 4.1.1: Background
- 4.1.2: Framework

#### 4.2: IVHM end-to-end system

- 4.2.1: Architecture
  - 4.2.2: IVHM lifecycle
  - 4.2.3: Functional model
  - 4.2.4: Operational model

#### 4.3: Vehicle level reasoning system

- 4.3.1: Fundamentals
- 4.3.2: Functional modules

#### 4.4: Aircraft applications

- 4.4.1: 777 aircraft diagnostic and maintenance system
- 4.4.2: Helicopter transmission HUMS
- 4.4.3: Embraer AHEAD program
- 4.4.4: Airbus AIRMAN program

#### 4.5: Autonomic logistic support

- 4.5.1: Definition
- 4.5.2: Application

#### 5) CONCLUSIVE REMARKS